

# Bragg Reflector Transfer Matrix Matlab

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2 controllers for the p-input/p-output cases, or to insert an extra pre-compensator compose of a static gain matrix. In this way, multiloop PID control system is constructed with p-PID controllers for the enlarged system. However, in the case of designing p2 controllers, it is intuitively difficult to understand the physical meaning of the PID gain because it is given as a matrix. On the other ...

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